



Baritone is a guitar which has always fascinated the human eye.  
Many believe that the musician who performs in a baritone is much  
more than the great number of people who are used  
for construction, for several instruments, for people, for artists,  
controlling and even, for...

The transmittal clearly that baritone offers us, holds a number of  
attributes for many. From an instrumental or technical point of view.

R6.smp >>>

# Applications of Neural Networks in Time-Series Analysis

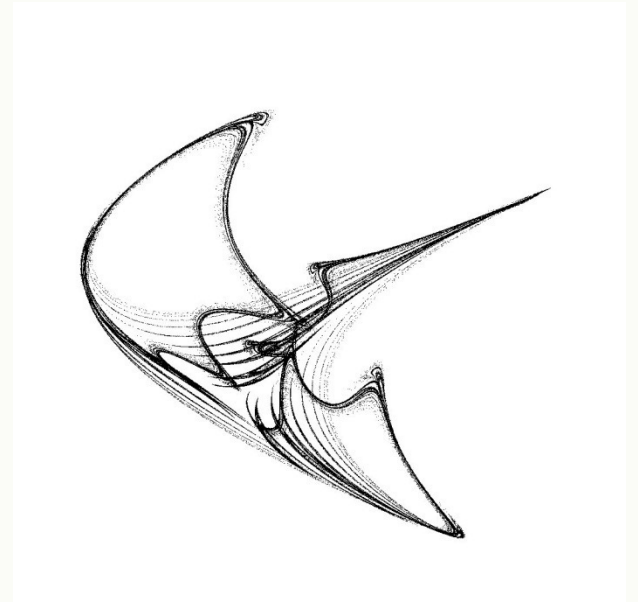
**Adam Maus**

Computer Science Department

**Mentor: Doctor Sprott**  
Physics Department

# Outline

- Discrete Time Series
- Embedding Problem
- Methods Traditionally Used
- Lag Space for a System
- Overview of Artificial Neural Networks
  - Calculation of time lag sensitivities
  - Comparison of model to known systems
- Comparison to other methods
- Results and Discussions



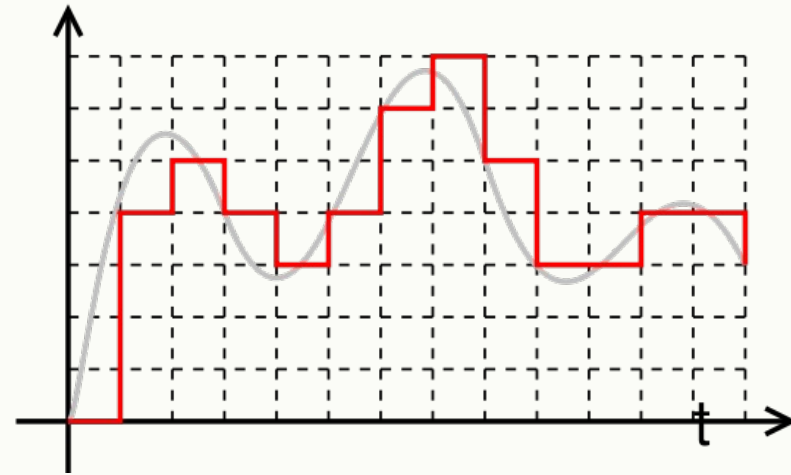
# Discrete Time Series

- Scalar chaotic time series
  - i.e. average daily temperatures

[45, 34, 23, 56, 34, 25, ...]

- Data given discrete intervals
  - i.e. seconds, days, etc.

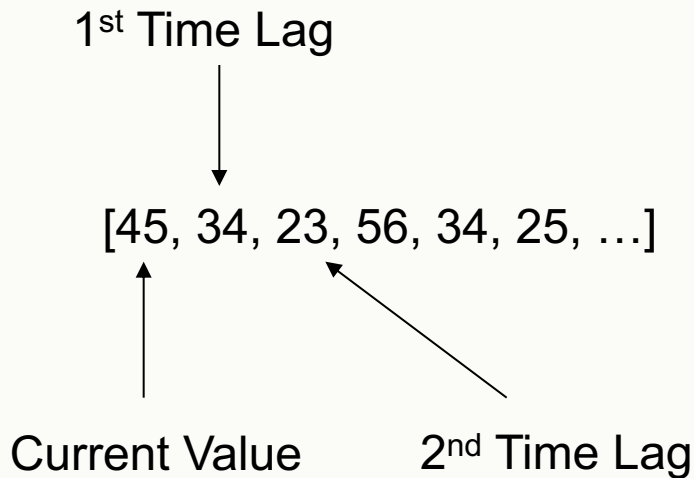
- We assume a combination of past values in the time series predict the future



Discrete Time Series (Wikimedia)

# Time Lags

- Each discrete interval refers to a dimension or time lag



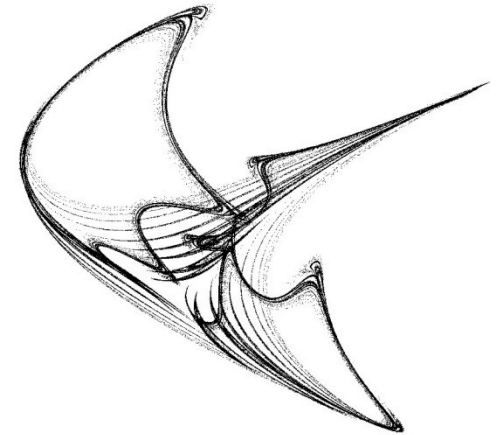
2<sup>nd</sup> Time Lag ....

$$x_k = x_{k-2} + x_{k-4} + x_{k-5}$$

Current Value

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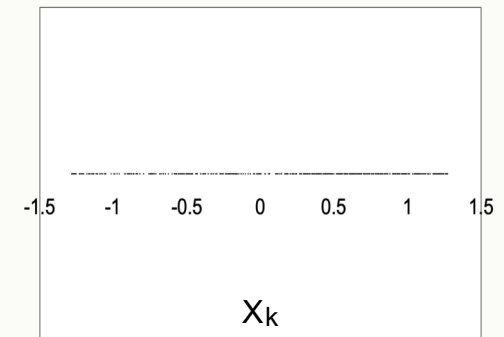
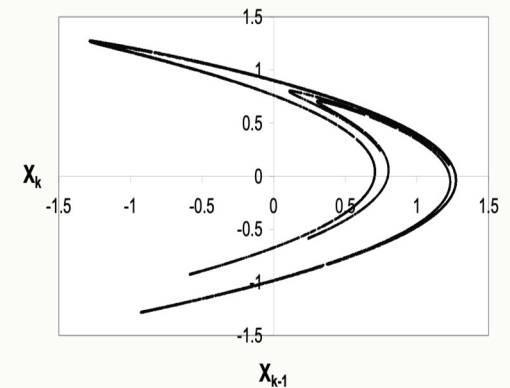
# Embedding Problem

**Problem: How do we choose the optimal embedding dimension that the model can use to unfold the data?**

- The embedding dimension is related to the minimum number of variables required to construct the data

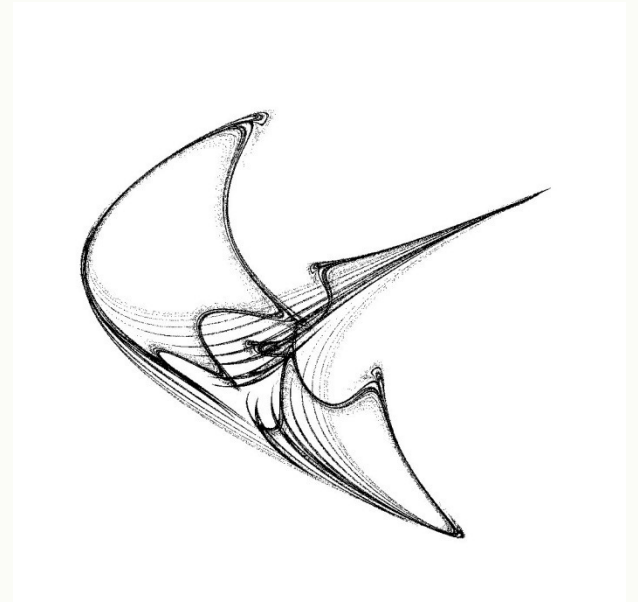
Or

- Exactly how many time lags are required to reconstruct the system without any information being lost but without adding unnecessary information
  - i.e. a ball seen in 2d, 3d, and 3d + Time



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# ARMA Models

- Autoregressive Moving Average Models
  - Fits a polynomial to the data based on linear combinations of past values

$$x_k = \beta + \varepsilon_t + \sum_{i=1}^d \alpha_i x_{k-i} + \sum_{i=1}^q \Theta_i \varepsilon_{k-i}$$

- Produces a linear function
- Can create very complicated dynamics but has difficulty with nonlinear systems

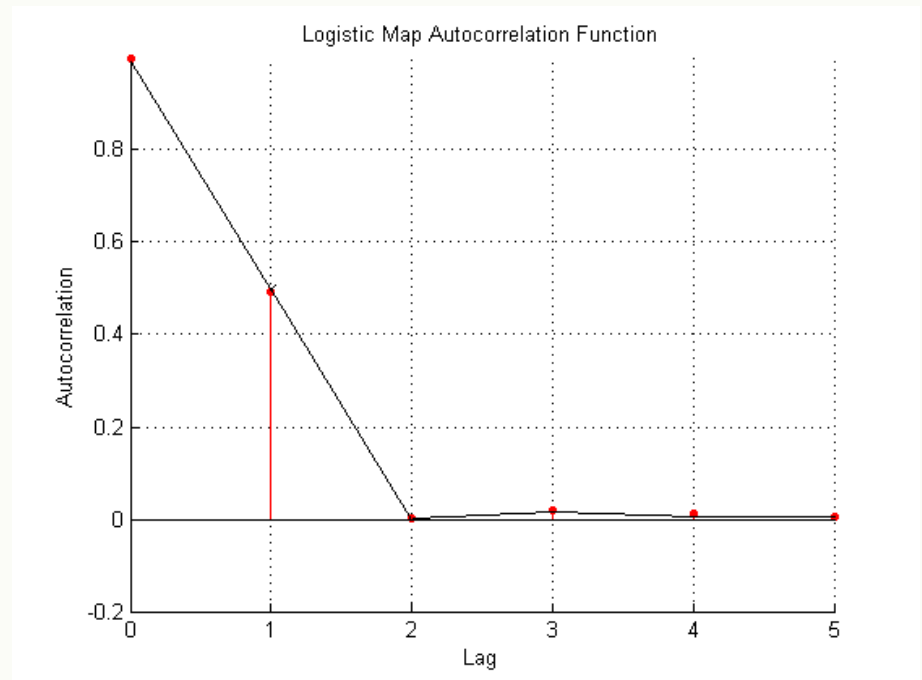


# Autocorrelation Function

- Finds correlations within data
- Much like the ARMA model, shows weak periodicity within nonlinear time series.
- No sense of the underlying dynamical system

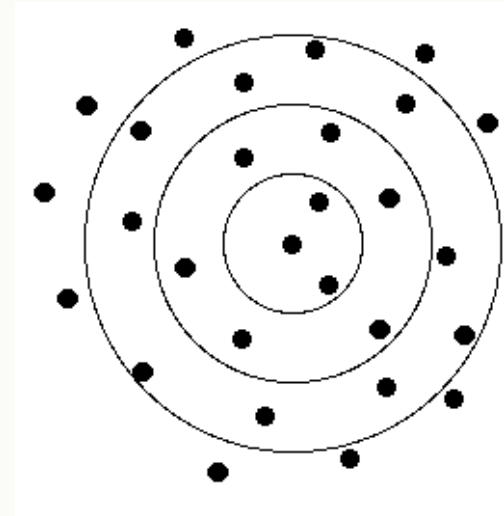
Logistic Map

$$x_k = 4x_{k-1}(1 - x_{k-1})$$



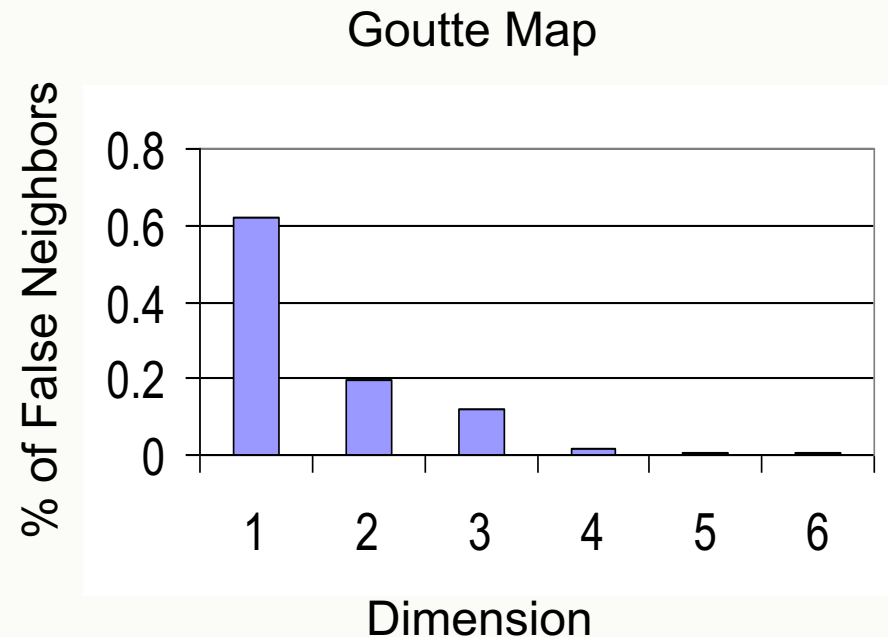
# Correlation Dimension

- Introduced in 1983 by Grassberger and Procaccia to find the fractal dimension of a chaotic system
- One can determine the embedding dimension by calculating the correlation dimension in increasing dimensions until it ceases to change
- Good for large datasets with little noise



# False Nearest Neighbors

- Introduced in 1992 by Kennel, Brown, and Abarbanel
- Calculation of false nearest neighbors in successively higher embedding dimensions
- As  $d$  is increased, the fraction of neighbors that are false drops to near zero
- Good for smaller datasets and rather robust to noise



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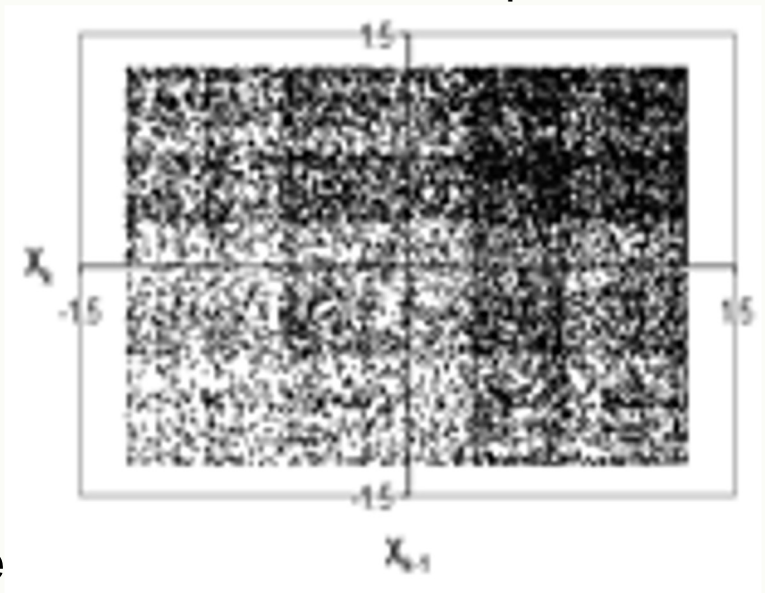
$$x_k = 0x_{k-1} + x_{k-2} + 0x_{k-3} + x_{k-4} + x_{k-5}$$

# Lag Space

- Not necessarily the same dimensions as embedding space
- Goutte Map dynamics depend only on the second and fourth time lag

**Problem: How can we measure both the embedding dimension and lag space?**

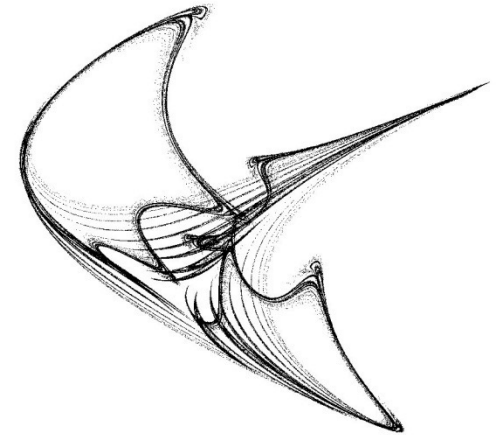
Goutte Map



$$x_k = 1 - 1.4x_{k-2}^2 - 0.3x_{k-4}$$

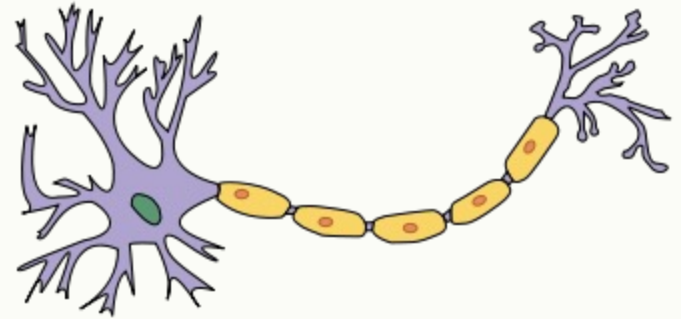
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# Artificial Neural Networks

- Mathematical Models of Biological Neurons
- Used in Classification Problems
  - Handwriting Analysis
- Function Approximation
  - Forecasting Time Series
  - Studying Properties of Systems



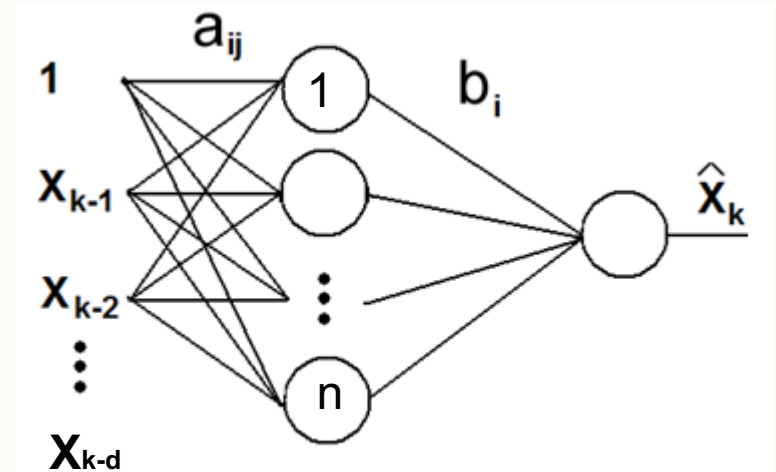
$$y_k = \phi \left( b_k + \sum_{j=1}^m a_{kj} x_j \right)$$

# Function Approximation

- Known as Universal Approximators
- The architecture of the neural network uses time-delayed data

$$x = [45, 34, 23, 56, 34, 25, \dots]$$

$$\hat{x}_k = \sum_{i=1}^n b_i \tanh \left( a_{i0} + \sum_{j=1}^d a_{ij} x_{k-j} \right)$$

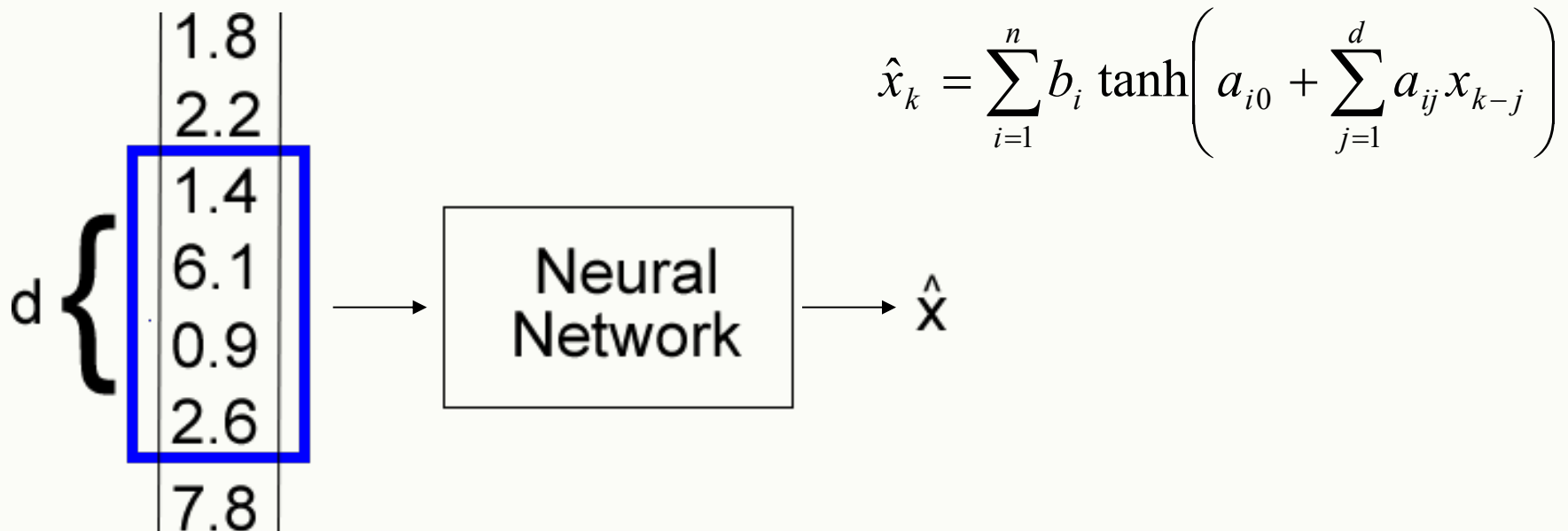


Structure of a Single-Layer Feed forward Neural Network



# Function Approximation

- Next Step Prediction
  - Takes  $d$  previous points and predicts the next step



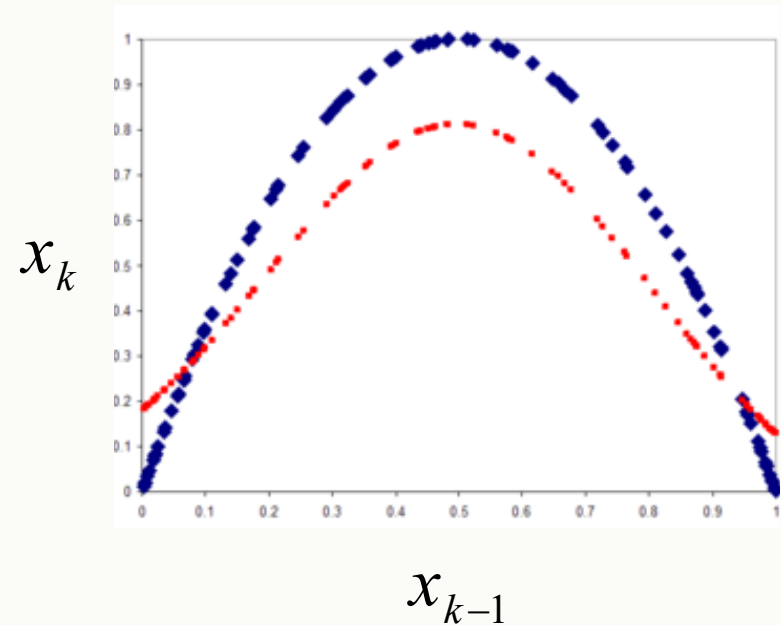
# Training

1. Initialize  $a$  matrix and  $b$  vector
2. Compare predictions  $\hat{x}_k$  to actual values  $x_k$

$$\text{Mean Square Error} = \frac{\sum_{k=1}^c (\hat{x}_k - x_k)^2}{c}$$

$c = \text{length of time series}$

3. Change parameters accordingly
4. Repeat millions of times



Fitting the **model** to **data** (Wikimedia)

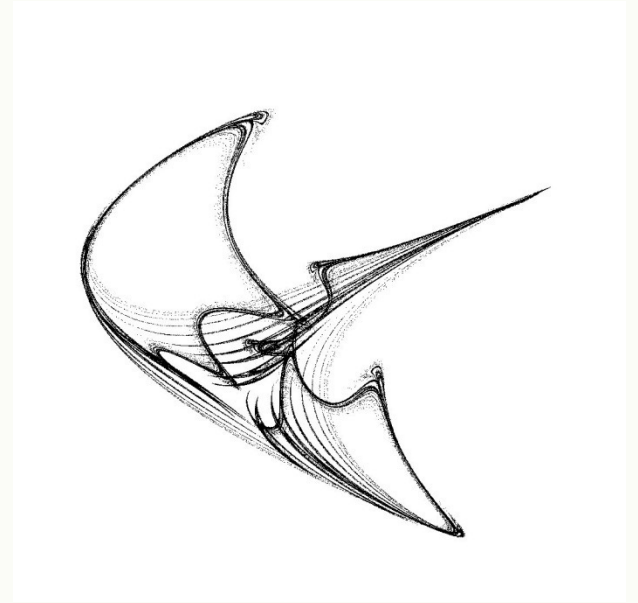
# Convergence

- The global optimum is found at the lowest mean square error
  - Connection strengths can be any real number
  - Like finding the lowest point in a mountain range
  
- Numerous low points so we must devise ways to avoid these local optimum



# Outline

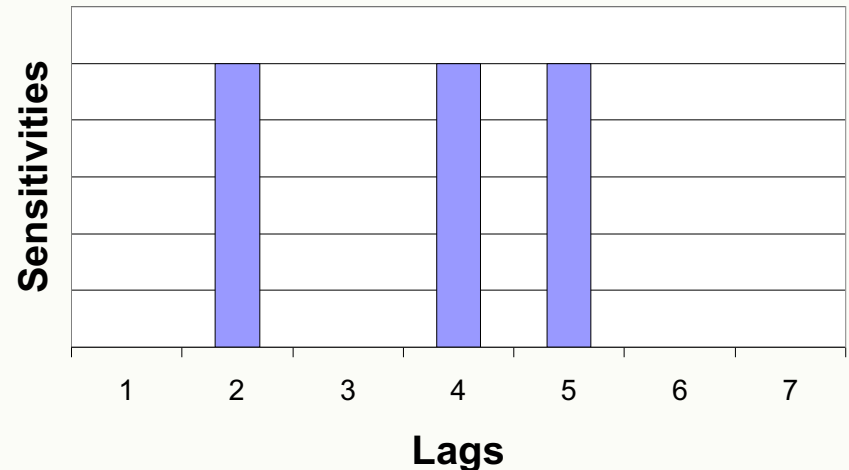
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# Time Lag Sensitivities

- We can train a neural network on data and study the model
- Find how much the output of the neural network varies when perturbing each time lag
- “Important” lags will have higher sensitivity to changes in values

$$x_k = x_{k-2} + x_{k-4} + x_{k-5}$$

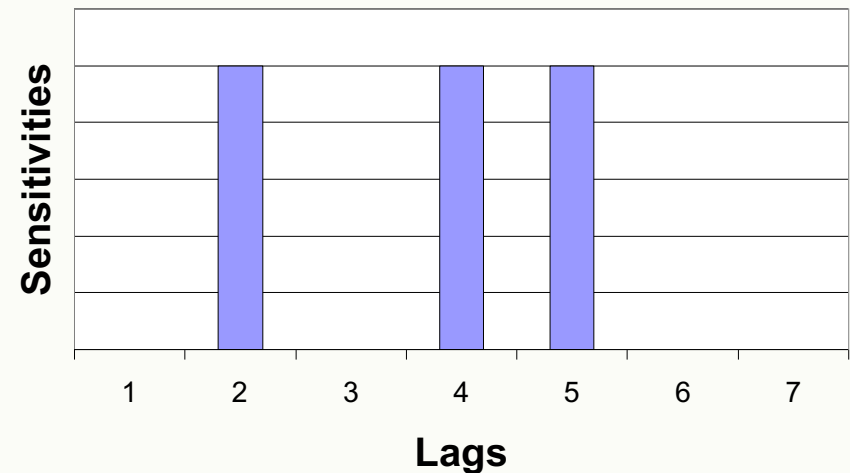


# Time Lag Sensitivities

- We estimate the sensitivity of each time lag in the neural network:

$$\hat{S}(j) = \frac{1}{c-j} \sum_{k=j+1}^c \left| \frac{\partial \hat{x}_k}{\partial x_{k-j}} \right|$$

$$\frac{\partial \hat{x}_k}{\partial x_{k-j}} = \sum_{i=1}^n a_{ij} b_i \operatorname{sech}^2 \left( a_{i0} + \sum_{m=1}^d a_{im} x_{k-m} \right)$$



# Expected Sensitivities

- For known systems we can estimate what the sensitivities should be

$$S(j) = \frac{1}{c-j} \sum_{k=j+1}^c \left| \frac{\partial \hat{x}_k}{\partial x_{k-j}} \right|$$

$$x_k = 1 - 1.4x_{k-1}^2 - 0.3x_{k-2}$$

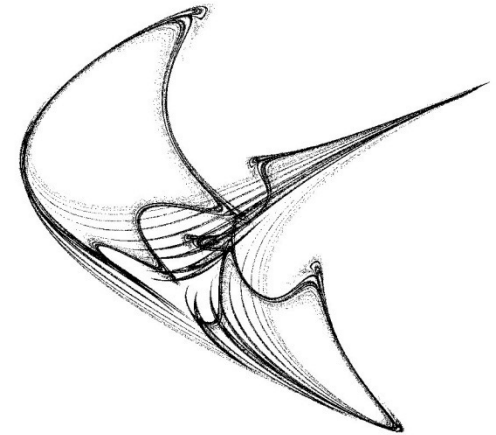
$$\frac{\partial x_k}{\partial x_{k-1}} = 2.8x_{k-1}$$

$$\frac{\partial x_k}{\partial x_{k-2}} = 0.3$$

- After training neural networks on data from different maps the difference between actual and expected sensitivities is <1%

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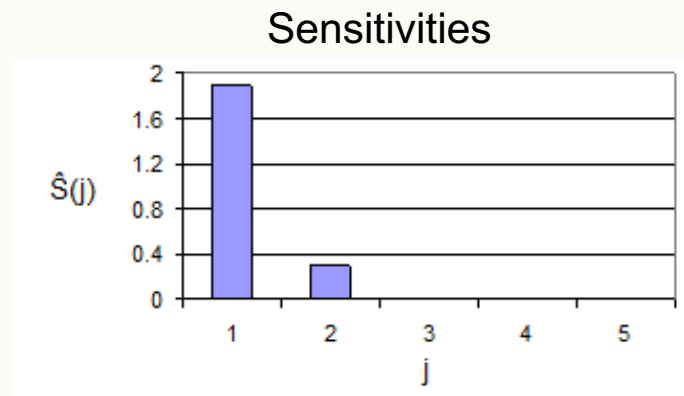




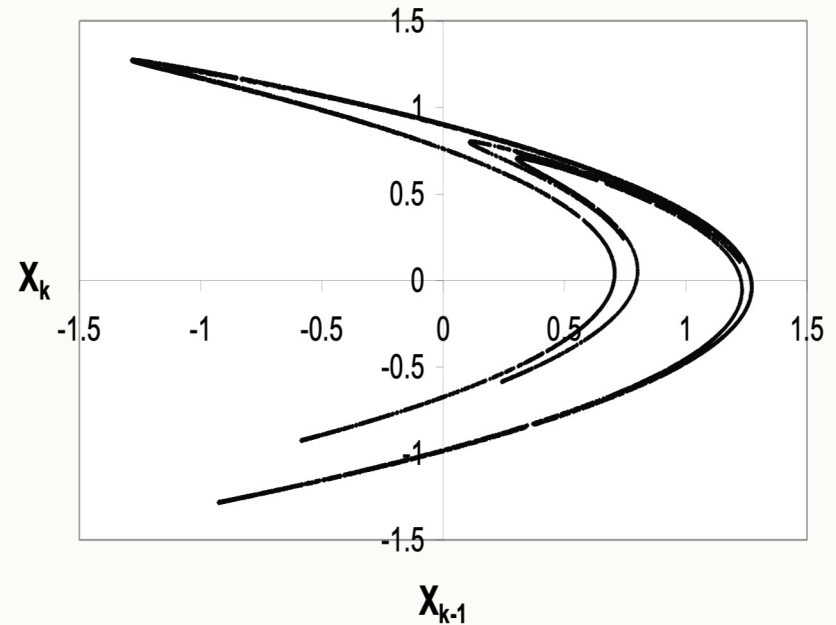
# Hénon Map

$$x_k = 1 - 1.4x_{k-1}^2 - 0.3x_{k-2}$$

Embedding of 2



$$S(1) = 1.8959 \quad S(2) = 0.3$$

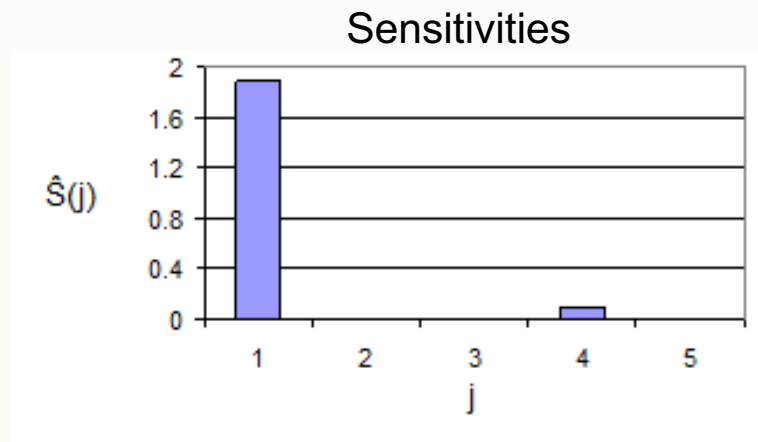


Strange Attractor of Hénon Map

# Delayed Hénon Map

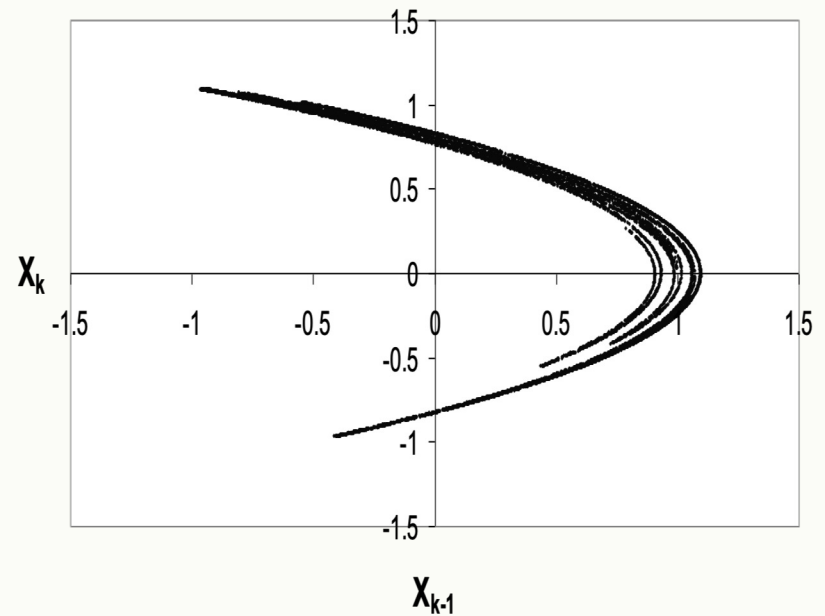
$$x_k = 1 - 1.6x_{k-1}^2 - 0.1x_{k-d}$$

Embedding of  $d$



$$S(1) = 1.9018$$

$$S(4) = .1$$

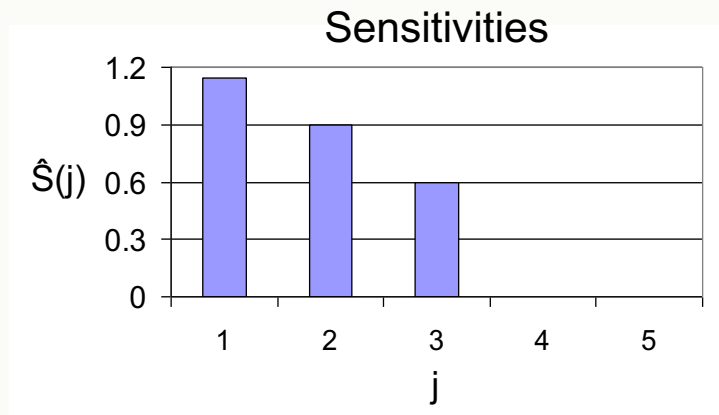


Strange Attractor of Delayed Hénon Map

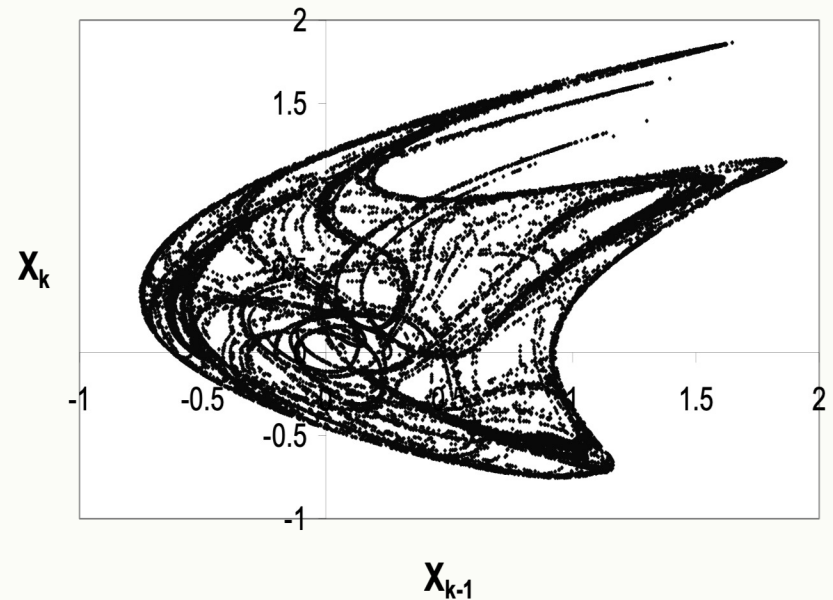
# Preface Map “The Volatile Wife”

$$x_k = x_{k-1}^2 - 0.2x_{k-1} - 0.9x_{k-2} + 0.6x_{k-3}$$

Embedding of 3



$$S(1) = 1.1502 \quad S(2) = 0.9 \quad S(3) = 0.6$$

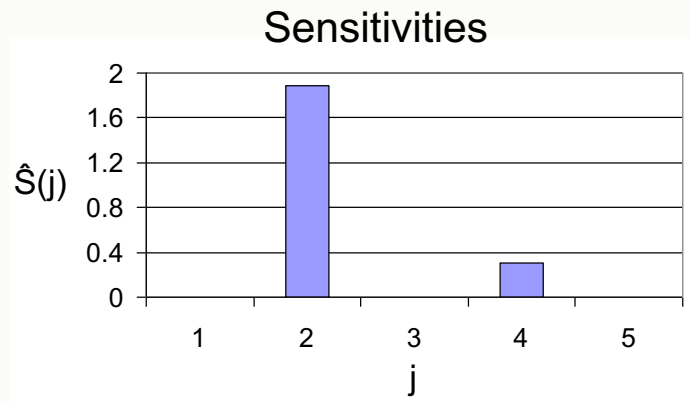


Strange Attractor of Preface Map

# Goutte Map

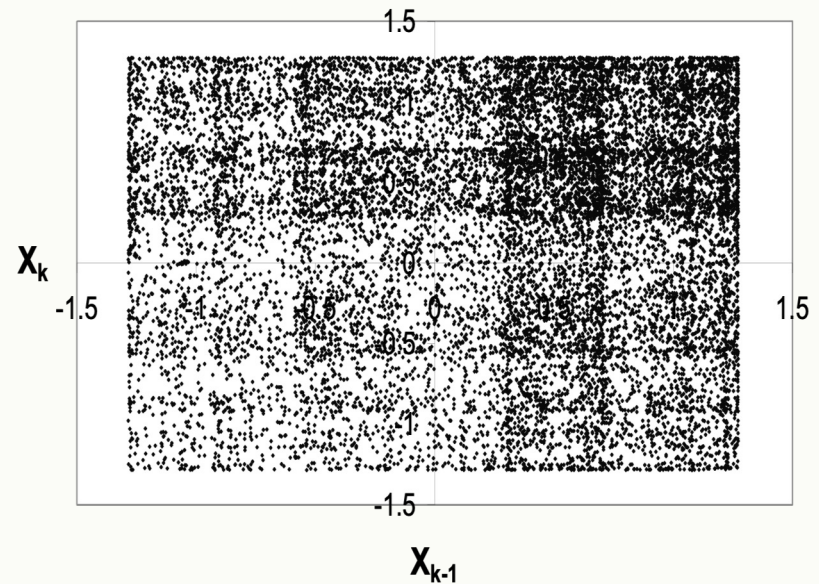
$$x_k = 1 - 1.4x_{k-2}^2 + 0.3x_{k-4}$$

Embedding of 4



$$S(2) = 1.8959$$

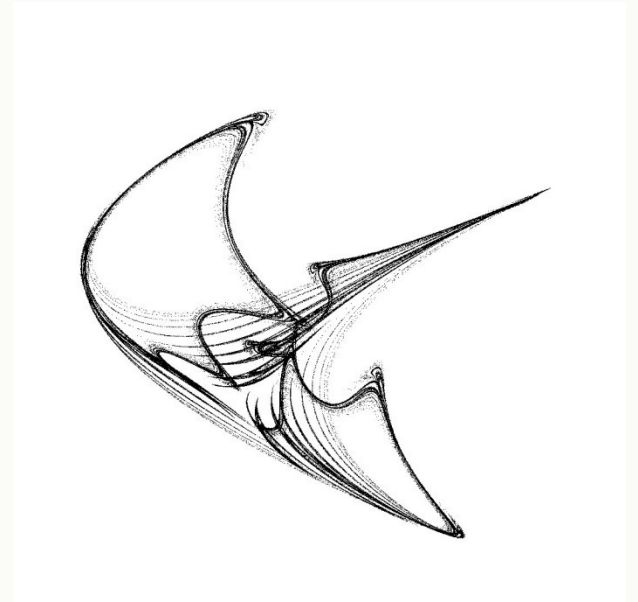
$$S(4) = 0.3$$



Strange Attractor of Goutte Map

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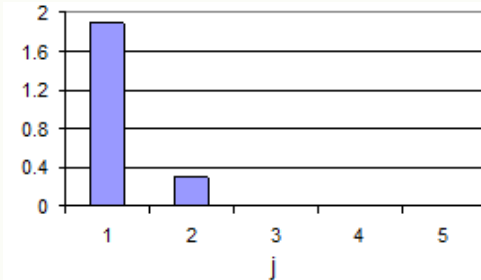
# Results from Other Methods

Hénon Map

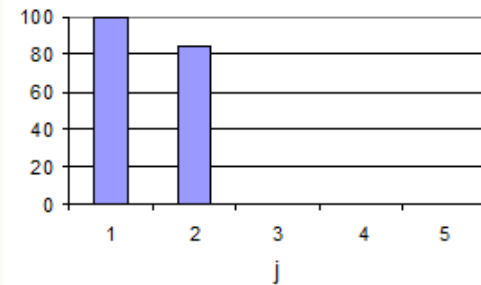
$$x_k = 1 - 1.4x_{k-1}^2 - 0.3x_{k-2}$$

Optimal Embedding of 2

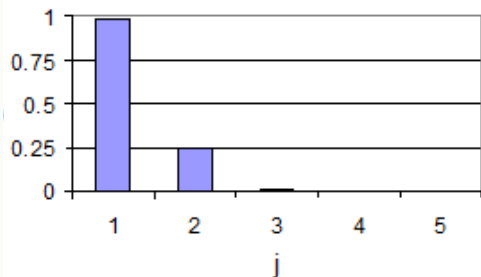
Neural  
Network



False Nearest  
Neighbors



Correlation  
Dimension



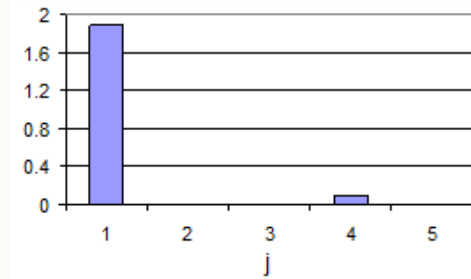
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Delayed Hénon Map

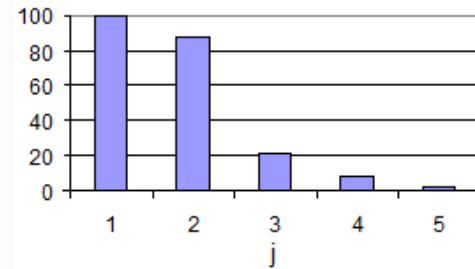
$$x_k = 1 - 1.6x_{k-1}^2 - 0.1x_{k-4}$$

Optimal Embedding of 4

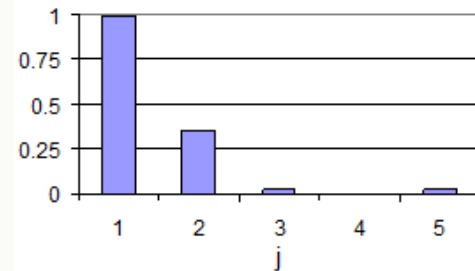
Neural Network



False Nearest Neighbors



Correlation Dimension



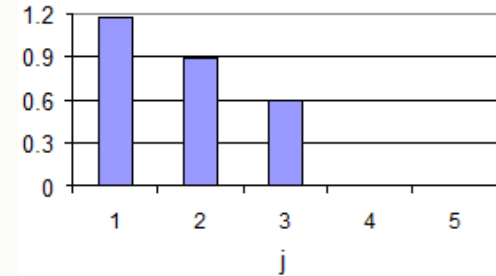
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Preface Map

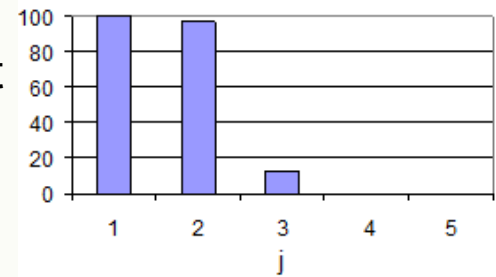
$$x_k = x_{k-1}^2 - 0.2x_{k-1} - 0.9x_{k-2} + 0.6x_{k-3}$$

Optimal Embedding of 3

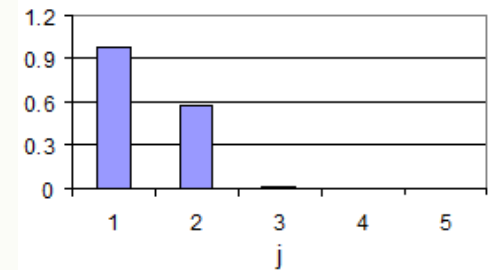
Neural Network



False Nearest Neighbors



Correlation Dimension





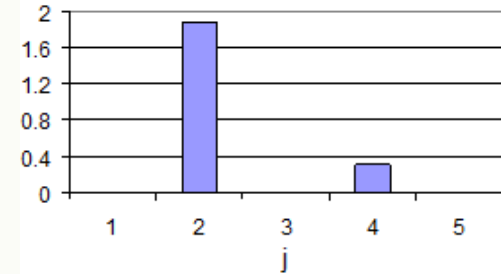
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Goutte Map

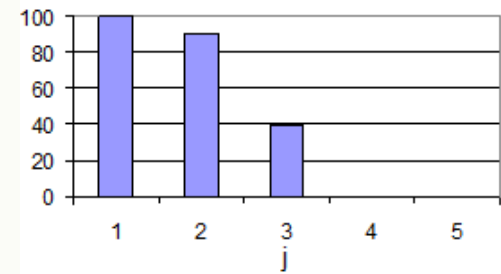
$$x_k = 1 - 1.4x_{k-2}^2 - 0.3x_{k-4}$$

Optimal Embedding of 4

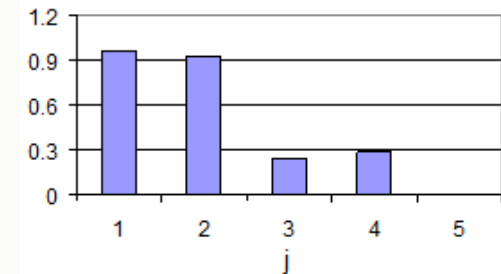
Neural Network



False Nearest Neighbors



Correlation Dimension

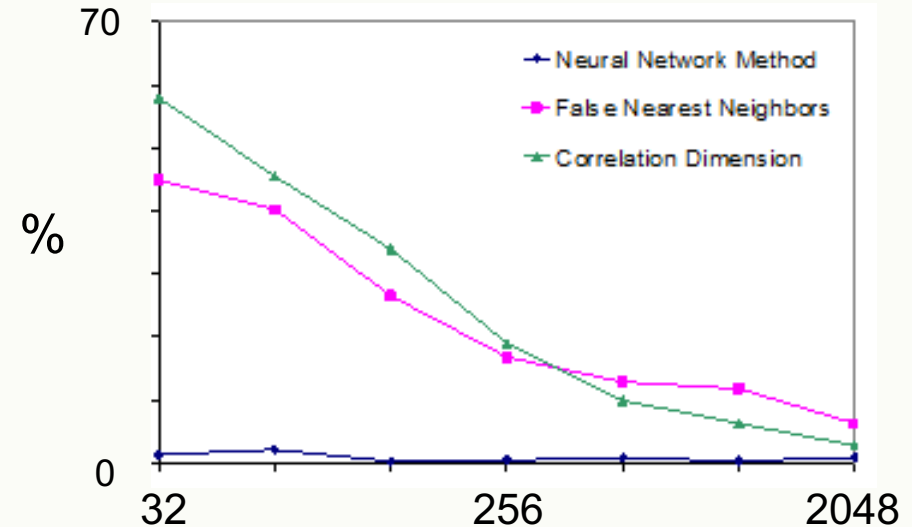


# Comparison using Data Set Size

- Varied the length of the Hénon map time series by powers of 2
- Compared methods to actual values using normalized RMS error  $E$

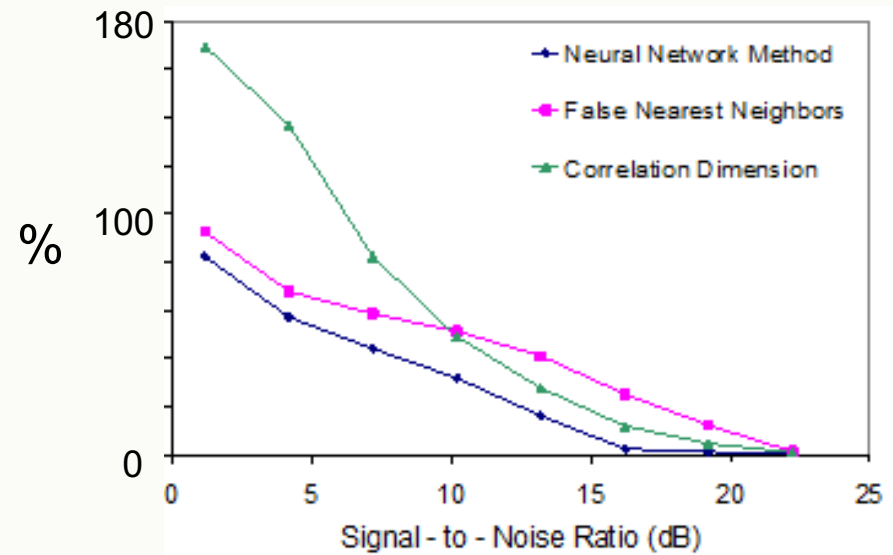
$$E = \sqrt{\frac{\sum_{j=1}^d (\hat{S}(j) - S(j))^2}{\sum_{j=1}^d S^2(j)}}$$

Where  $\hat{S}$  is predicted value for a test data set size  
 $S$  is actual value for an ideal data set size  
 $j$  is one dimension of  $d$  that we are studying



# Comparison using Noisy Data Sets

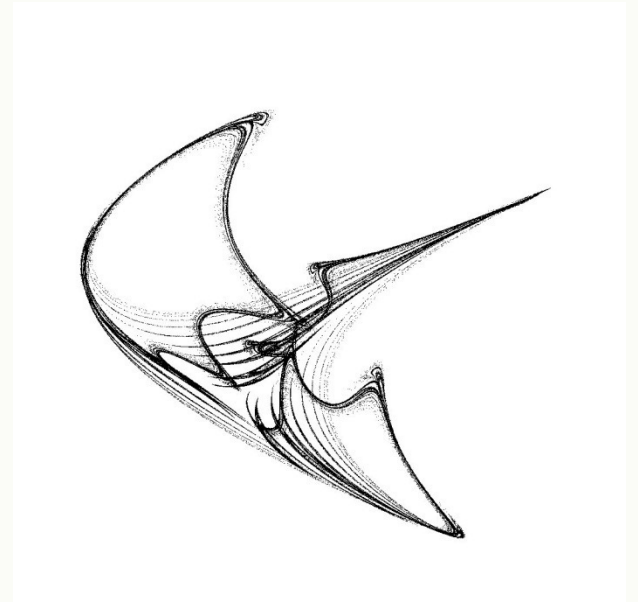
- Vary the noise in the system by adding Gaussian White Noise to a fixed length time series from the Hénon Map
- Compared methods to actual values using normalized RMS error
- Used noiseless case values for comparison of methods



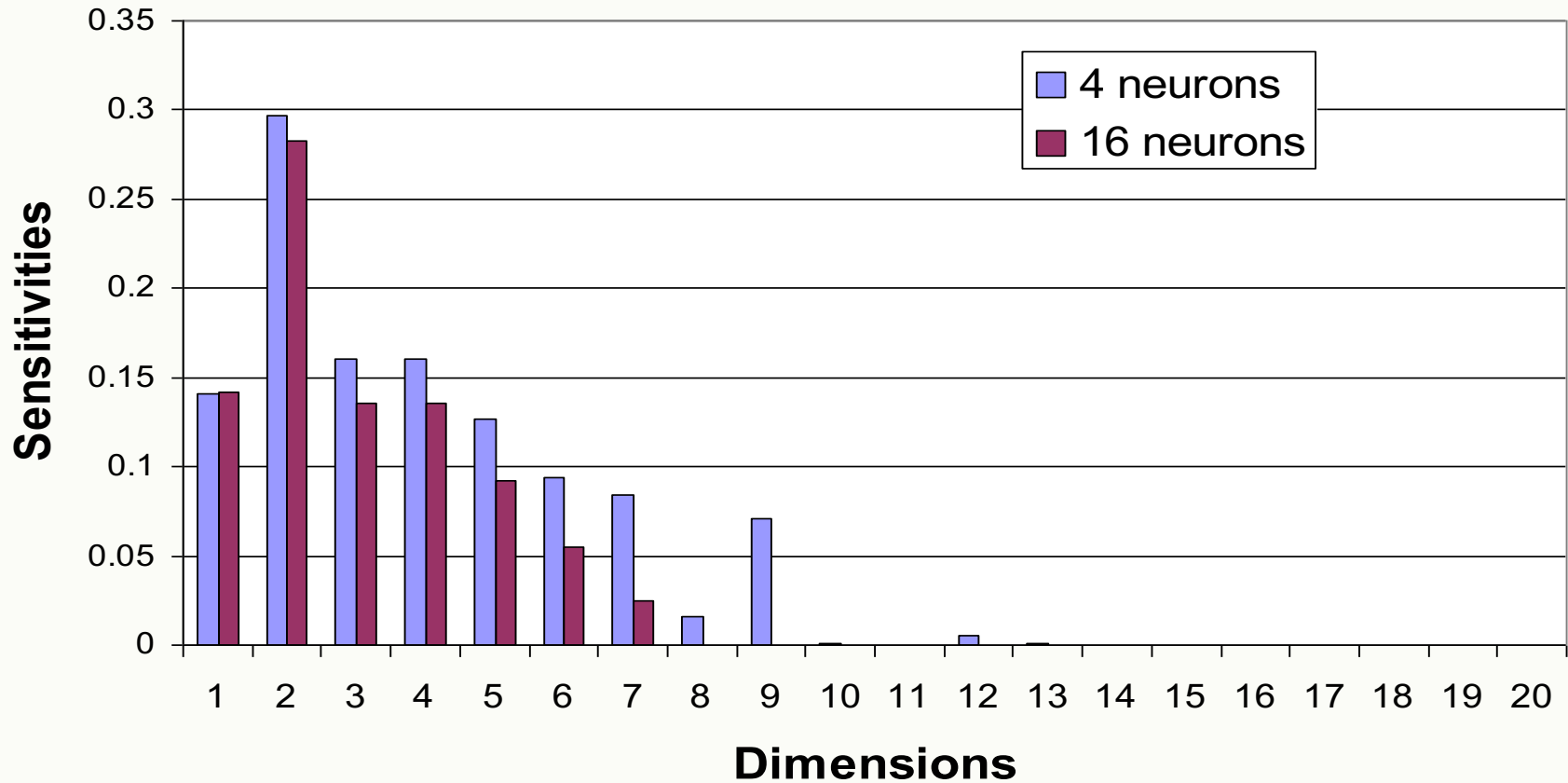
High Noise ← ————— → Low Noise

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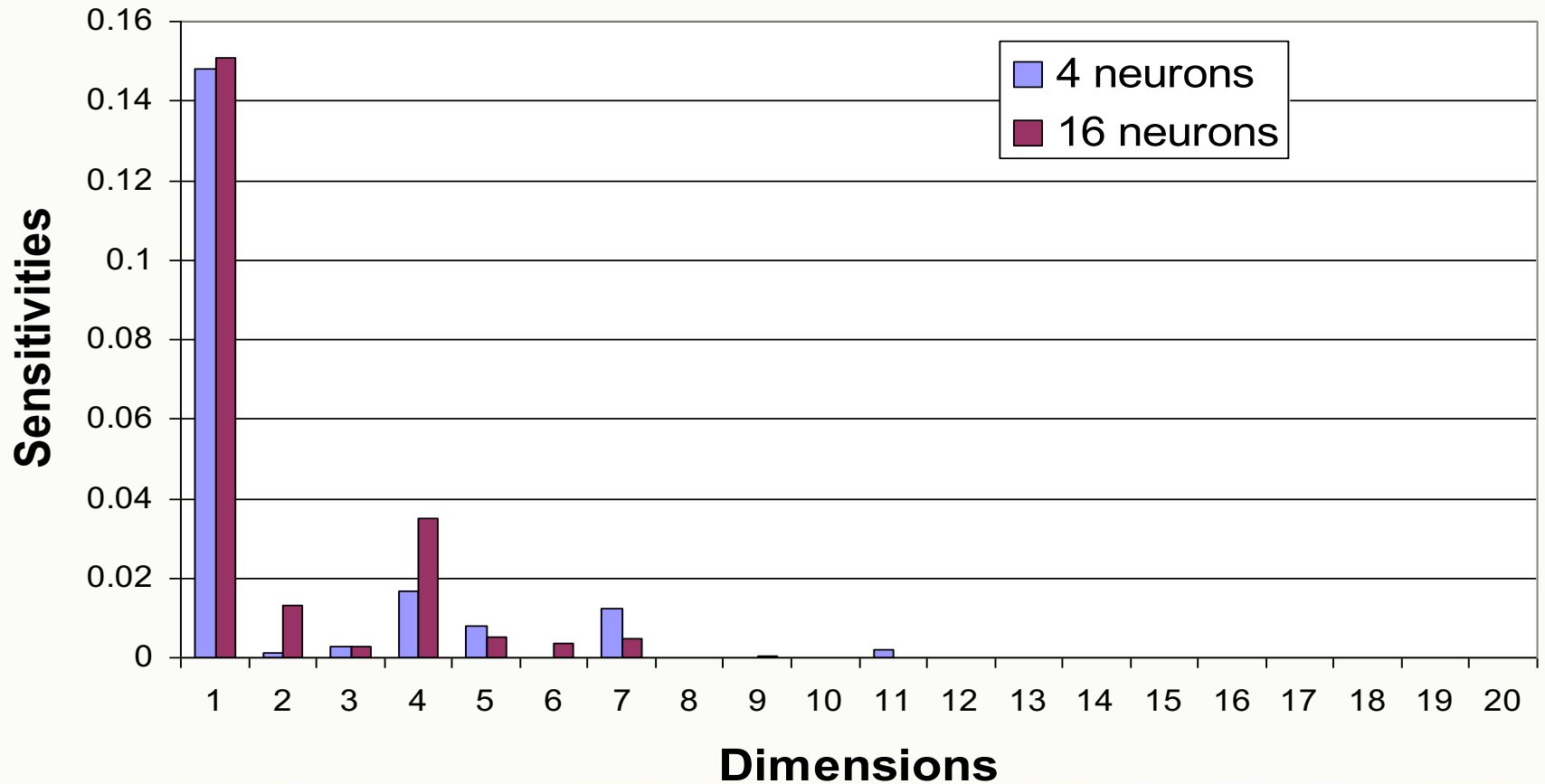
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# Temperature in Madison

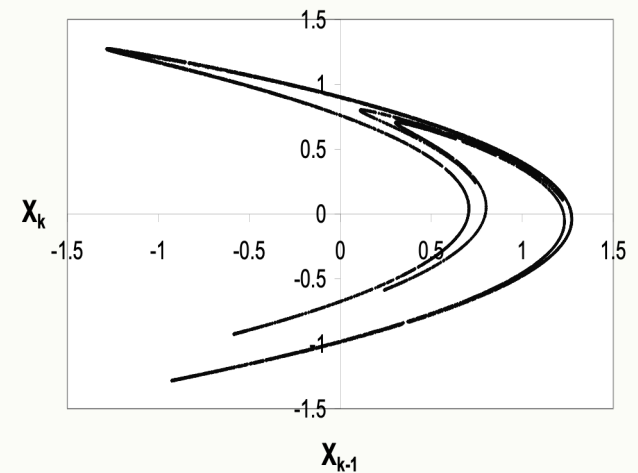


# Precipitation in Madison



# Summary

- Neural networks are models that can be used to predict the embedding dimension
- They can handle small datasets and accurately predict sensitivities for a given system
- They prove to be more robust to noise than other methods used
- They can be used to determine the lag space where methods cannot



# Acknowledgments

- Doctor Sprott for guiding this project
- Doctor Young and Ed Hopkins at the State Climatology Office for the weather data and insightful discussions